

## EDGE CORRECTING CIRCUIT

## BACKGROUND OF THE INVENTION

The present invention relates to an edge correcting circuit for correcting the edge of the image represented by a digital image signal.

In a display device used as a display terminal for a personal computer or a television set, edge correction by means of digital signal processing is adopted as a method for enhancing the edge of the displayed image to improve the sharpness. Generally, a high-frequency signal is extracted by passing the digital image signal through digital filters, and adding the high-frequency signal to the original signal, to obtain the edge-corrected image signal.

Fig. 16 is a diagram showing a conventional edge correcting circuit. This edge correcting circuit comprises an input terminal 101 for receiving a digital image signal Sa, a one-pixel delay unit 1 for delaying the signal Sa by one pixel period to output a signal Sb, a one-pixel delay unit 2 for delaying the signal Sb by one pixel period to output a signal Sc, a one-pixel delay unit 3 for delaying the signal Sc by one pixel period to output a signal Sd, a one-pixel delay unit 4 for delaying the signal Sd by one pixel period to output a signal Se, a high-frequency extracting circuit 5 formed of digital filters, an adder 8, and an output terminal 102 for outputting the edge-corrected image signal.

The operation of the conventional edge correcting circuit will next be described with reference to Figs. 17A to 17E.

First, let us assume that an image signal Sa shown in Fig. 17A is applied to the input terminal 101. The image signal Sa is successively delayed by the one-pixel delay units 1, 2, 3 and 4 to result in the signals Sb, Sc, Sd and Se. Figs. 17B and 17C show the signals Sc and Se.

The high-frequency signal extracting circuit 5 performs calculation using the signals Sa, Sc and Se, to produce a

high-frequency signal  $S_f$  shown in Fig. 17D. The signal Fig. 17D is a high-frequency signal whose amplitude is maximum at the rising and falling parts of the input signal ( $S_a$ ).

As an example, the high-frequency signal extracting circuit 5 multiplies the input signals  $S_a$ ,  $S_c$  and  $S_e$  by the coefficients  $-1/4$ ,  $1/2$  and  $-1/4$ , and adds the products together, and adjusts the amplitude as required. When the amplitude is quadrupled by the amplitude adjustment, the output signal  $S_f$  will represent  $S_f = -S_a + 2S_c - S_e$ , as illustrated.

The high-frequency signal  $S_f$  output from the high-frequency extracting circuit 5 is added at the adder 8 to the original signal  $S_c$  with its delay due to the high-frequency extracting circuit 5 compensated. As a result, a signal  $S_p$  obtained by the edge-correction is as shown in Fig. 17E. In Fig. 17E, values less than 0 are shown, but in the case where the signal is used for display in a display device, the values less than 0 are clipped.

The conventional edge correcting circuit as described above is associated with excessive overshoots and undershoots (they both will be referred to simply as "overshoots") at the edge parts. It is possible to make the overshoot less prominent by reducing the high-frequency signal by the amplitude adjustment within the high-frequency extracting circuit 5, but in that case the necessary edge enhancement cannot be made adequately.

#### SUMMARY OF THE INVENTION

The invention has been made to solve the problems described above, and its object is to provide an edge correcting circuit which can reduce or eliminate the overshoot, and which can fully achieve the necessary edge enhancement.

According to one aspect of the invention, there is provided an edge correcting circuit of an image to be represented by a digitized image signal, comprising:

a high-frequency signal extracting circuit for extracting a high-frequency signal of the image by calculation based on

a signal of a pixel which is to be corrected (hereinafter called a target pixel), a signal of a pixel shifted from the target pixel by  $m$  ( $m$  being an integer not smaller than 2) pixels in the right or lower direction, and a signal of a pixel shifted from the target pixel by  $m$  pixels in the left or upper direction;

an amplitude-restricting signal generator for determining an amplitude-restricting signal based on a minimum value or a maximum value of an absolute value of a difference between the signal of the target pixel and a signal of a pixel shifted from the target pixel by  $n$  ( $n$  being an integer not smaller than 1 and smaller than  $m$ ) pixels in the right or lower direction, and an absolute value of a difference between the signal of the target pixel and a signal of a pixel shifted from the target pixel by  $n$  pixels in the left or upper direction;

an amplitude restricting circuit for restricting the output of the high-frequency extracting circuit so that the absolute value of the output of the high-frequency extracting circuit is not more than the output of the amplitude-restricting signal generator; and

an adder for adding the output of the amplitude restricting circuit or a signal obtained therefrom, as an edge correction signal, to the signal of the target pixel.

With the above arrangement, it is possible to obtain an edge-corrected image signal with the horizontal or vertical overshoots having been reduced or removed.

The high-frequency extracting circuit may have the function of altering the amplitude of the high-frequency signal output therefrom.

With the above arrangement, the amount of the edge enhancement can be adjusted depending on the state of the input signal.

The amplitude-restricting signal generator may have the function of altering the amplitude of the amplitude-restricting signal output therefrom.

With the above arrangement, it is possible to adjust the

amount of overshoot mixed, so as to realize a desired degree of sharpness.

The edge correcting circuit may further comprise:

a subtractor for subtracting the output of the amplitude restricting circuit from the output of the high-frequency extracting circuit;

an amplitude control circuit for controlling the amplitude of the output of the subtractor; and

a second adder for adding the output of the amplitude control circuit and the output of the amplitude restricting circuit;

wherein the output of the second adder is used as the edge correction signal.

With the above arrangement, it is possible to adjust the overshoot components and the components improving the edge inclination independently of each other, so as to optimize the edge correction.

The edge correcting circuit may further comprise:

a subtractor for subtracting the output of the amplitude restricting circuit from the output of the high-frequency extracting circuit;

an amplitude adjusting circuit for adjusting the amplitude of the output of the amplitude restricting circuit; and

a second adder for adding the output of the subtractor and the output of the amplitude adjusting circuit;

wherein the output of the second adder is used as said edge correction signal.

With the above arrangement, it is possible to adjust the overshoot components and the components improving the edge inclination independently of each other, so as to optimize the edge correction.

According to another aspect of the invention, there is provided an edge correcting circuit of an image to be represented by a digitized image signal, comprising:

a high-frequency signal extracting circuit for extracting a high-frequency signal of the image by calculation based on

a signal of a pixel which is to be corrected (hereinafter called a target pixel), a signal of a pixel shifted from the target pixel by  $m$  ( $m$  being an integer not smaller than 2) pixels in the right or lower direction, and a signal of a pixel shifted from the target pixel by  $m$  pixels in the left or upper direction;

an amplitude-restricting signal generator for determining an amplitude-restricting signal based on a difference between the signal of the target pixel and a signal of a pixel shifted from the target pixel by  $n$  ( $n$  being an integer not smaller than 1 and smaller than  $m$ ) pixels in the right or lower direction, and a difference between the signal of the target pixel and a signal of a pixel shifted from the target pixel by  $n$  pixels in the left or upper direction;

an amplitude restricting circuit for restricting the output of the high-frequency extracting circuit so that the absolute value of the output of the high-frequency extracting circuit is not more than the output of the amplitude-restricting signal generator; and

an adder for adding the output of the amplitude restricting circuit or a signal obtained therefrom, as an edge correction signal, to the signal of the target pixel;

wherein

said amplitude-restricting signal generator outputs "0" when a first difference value obtained by subtracting the signal of the target pixel from the signal of the pixel shifted by  $n$  pixels from the target pixel in the right or lower direction, and a second difference value obtained by subtracting the signal of the target pixel from the signal of the pixel shifted by  $n$  pixels from the target pixel in the left or upper direction are of the same sign (or at least one of them is zero), and

said amplitude-restricting signal generator selectively outputs that one of the first and second difference values which is of the same sign as the output of the high-frequency extracting circuit, when neither of the first and second difference values is zero, and the first and second difference values have

different signs.

With the above arrangement, it is possible to obtain an edge-corrected image signal with the horizontal or vertical overshoots having been reduced or removed.

The high-frequency extracting circuit may have the function of altering the amplitude of the high-frequency signal output therefrom.

With the above arrangement, the amount of the edge enhancement can be adjusted depending on the state of the input signal.

The amplitude-restricting signal generator may have the function of altering the amplitude of the amplitude-restricting signal output therefrom.

With the above arrangement it is possible to adjust the amount of overshoot mixed, so as to realize a desired degree of sharpness.

The edge correcting circuit may further comprise:

a subtractor for subtracting the output of the amplitude restricting circuit from the output of the high-frequency extracting circuit;

an amplitude control circuit for controlling the amplitude of the output of the subtractor; and

a second adder for adding the output of the amplitude control circuit and the output of the amplitude restricting circuit;

wherein the output of the second adder is used as the edge correction signal.

With the above arrangement, it is possible to adjust the overshoot components and the components improving the edge inclination independently of each other, so as to optimize the edge correction.

The edge correcting circuit may further comprise:

a subtractor for subtracting the output of the amplitude restricting circuit from the output of the high-frequency extracting circuit;

an amplitude adjusting circuit for adjusting the amplitude

of the output of the amplitude restricting circuit; and  
 a second adder for adding the output of the subtractor and  
 the output of the amplitude adjusting circuit;  
 wherein the output of the second adder is used as said edge  
 correction signal.

With the above arrangement, it is possible to adjust the  
 overshoot components and the components improving the edge  
 inclination independently of each other, so as to optimize the  
 edge correction.

#### BRIEF DESCRIPTION OF THE DRAWINGS

In the drawings:-

Fig. 1 is a block diagram showing an edge correcting circuit  
 of Embodiment 1 of the invention;

Figs. 2A to 2F are diagrams showing signals appearing at  
 various parts of the circuit of Embodiment 1 of the invention;

Figs. 3A to 3G are diagrams showing signals appearing at  
 various parts of the circuits of Embodiment 1 of the invention;

Fig. 4 is a block diagram showing a high-frequency signal  
 extracting circuit used in Embodiment 1 of the invention;

Fig. 5 is a block diagram showing an amplitude-restricting  
 signal generator used in Embodiment 1 of the invention;

Fig. 6 is a block diagram showing an amplitude restricting  
 circuit used in Embodiment 1 of the invention;

Fig. 7 is a block diagram showing an edge correcting circuit  
 of Embodiment 2 of the invention;

Figs. 8A to 8H are diagrams showing signals appearing at  
 various parts of the circuit of Embodiment 2 of the invention;

Fig. 9 is a block diagram showing an edge correcting circuit  
 of Embodiment 3 of the invention;

Figs. 10A to 10G are diagrams showing signals appearing at  
 various parts of the circuit of Embodiment 3 of the invention;

Fig. 11 is a block diagram showing an amplitude-restricting  
 signal generator used in Embodiment 3 of the invention;

Fig. 12 is a block diagram showing an edge correcting circuit

of Embodiment 4 of the invention;

Fig. 13 is a block diagram showing an amplitude-restricting signal generator used in Embodiment 4 of the invention;

Figs. 14A to 14G are diagrams showing signals appearing at various parts of the circuit of Embodiment 5 of the invention;

Fig. 15 is a block diagram showing an edge correcting circuit of Embodiment 6 of the invention;

Fig. 16 is a block diagram showing a conventional edge correcting circuit; and

Figs. 17A to 17E are diagrams showing signals at various parts of the conventional edge correcting circuit.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Embodiments of the invention will next be described with reference to Fig. 1 to Fig. 15.

##### Embodiment 1.

Fig. 1 is an edge correcting circuit of Embodiment 1 of the invention. Figs. 2A to 2F, and Figs. 3A to 3G show signals at various parts of the edge correcting circuit.

As shown in Fig. 1, the edge correcting circuit has an input terminal 101 for receiving a digitized image signal Sa formed of a sequence of digitized pixel signals representing luminance or colors of respective pixels, four one-pixel delay units 1, 2, 3 and 4 connected in series with each other, a high-frequency extracting circuit 5, an amplitude-restricting signal generator 6, an amplitude restricting circuit 7, an adder 8, and an output terminal 102 for outputting the edge-corrected image signal.

The image signal Sa input to the input terminal 101 is delayed successively by the one-pixel delay units 1, 2, 3 and 4 to become output signals Sb, Sc, Sd and Se (Fig. 2B, Fig. 2C, Fig. 2D and Fig. 2E) of the respective delay units.

The high-frequency extracting circuit 5 is formed of digital filters, and performs a predetermined calculation on them, to generate a high-frequency signal Sf shown in Fig. 2F. The signal Sf is a high-frequency signal with its magnitude being maximum



at the rising and falling parts of the input signal.

Fig. 4 shows details of the high-frequency extracting circuit 5. As illustrated, the high-frequency extracting circuit 5 has an input terminal 501 receiving the signal  $S_a$ , an input terminal 502 receiving the signal  $S_c$ , an input signal 503 receiving the signal  $S_e$ , coefficient multipliers 51, 52, and 53 multiplying the signals input at the input terminals 501, 502 and 503 by coefficients  $-1/4$ ,  $1/2$ , and  $-1/2$ , an adder 54 for adding together the outputs of the coefficient multipliers 51, 52 and 53, and an amplitude adjusting circuit 55 for adjusting the amplitude of the output of the adder 54.

The signal  $S_c$  is called a signal of a target pixel for the reason explained later. The signal  $S_a$  is a signal of a pixel shifted rightward by two pixels from the target pixel, and the signal  $S_e$  is a signal of a pixel shifted leftward by two pixels from the target pixel.

The signals  $S_a$ ,  $S_c$  and  $S_e$  are multiplied by coefficients  $-1/4$ ,  $1/2$  and  $-1/4$  at the coefficient multipliers 51, 52 and 53, and the products are added together at the adder 54. The output of the adder 54 is input to the amplitude adjusting circuit 55 where its amplitude is adjusted, and the amplitude-adjusted signal  $S_f$  is supplied to the output terminal 504. The amplitude adjusting circuit 55 varies the amount of edge enhancement in accordance with the state of the input signal. Figs. 2A to 2F show the case where the amplitude is quadrupled by the amplitude adjusting circuit 55. In this case, the signal  $S_f$  will be given by  $f = -S_a + 2S_c - S_e$ . The output terminal 504 is connected to the input of the amplitude restricting circuit 7.

The amplitude-restricting signal generator 6 generates the amplitude-restricting signal  $S_i$  based on the signals  $S_b$  and  $S_c$ , and supplies it to the amplitude restricting circuit 7. Fig. 5 shows details of the amplitude-restricting signal generator 6. As illustrated, it comprises an input terminal 601 for receiving the signal  $S_c$ , an input terminal 602 for receiving the signal  $S_b$ , a subtractor 61 for subtracting the signal  $S_c$

from the signal  $S_b$ , an absolute value circuit 62 for determining the absolute value  $S_g$  (Fig. 3C) of the result of the subtraction at the subtractor 61, a one-pixel delay unit 63 for delaying the output of the absolute value circuit 62 by one pixel period to output a delayed signal  $S_h$ , a minimum value selector 64, and an amplitude adjusting circuit 65.

The delayed signal  $S_h$  is equivalent to the absolute value of the difference between the signals  $S_c$  and  $S_d$ . The minimum value selector 64 receives the signals  $S_g$  and  $S_h$  and selectively outputs the smaller one of them. The amplitude adjusting circuit 65 adjusts the amplitude of the output of the minimum value selector 64, and supplies the signal shown in Fig. 3E, to the output terminal 603. The output terminal 603 is connected to the input of the amplitude restricting circuit 7.

The amplitude restricting circuit 7 restricts the amplitude so that the absolute value of the input high-frequency signal  $S_f$  does not exceed the amplitude-restricting signal  $S_i$ , and supplies the amplitude-restricted high-frequency signal  $S_j$  to the adder 8. Fig. 6 shows details of the amplitude restricting circuit 7. As illustrated, the amplitude restricting circuit 7 has an input terminal 701 for receiving the output signal  $S_f$  of the high-frequency extracting circuit 5, an input terminal 702 for receiving the output signal  $S_i$  of the amplitude-restricting signal generator 6, an absolute value circuit 71 for determining the absolute value of the signal  $S_f$ , and a comparator 72 for comparing the output signal of the absolute value circuit 71 with the signal  $S_i$ , a sign inverting circuit 73 for inverting the sign of the signal  $S_i$ , a first selector 74, a first selector 74, a second selector 75, and an output terminal 203.

The first selector 74 selectively outputs the signal  $S_i$  when the sign of the signal  $S_f$  is positive, and selectively outputs the output signal of the sign inverting circuit 73 when the sign of the signal  $S_f$  is negative. The second selector 75 selects

the signal  $S_f$  when the output signal of the absolute value circuit 71 is smaller than the signal  $S_i$ , and selects the output signal of the selector 74 at other times, and outputs the signal  $S_j$  as shown in Fig. 3F. The output signal  $S_j$  of the selector 75 is supplied via the output terminal 703 to the adder 8.

The adder 8 adds the amplitude-restricted high-frequency signal  $S_j$  to the signal  $S_c$  of the target pixel output from the one-pixel delay unit 2, and supplies the edge-corrected image signal  $S_p$  to the output terminal 102. The reason for using the output  $S_c$  of the one-pixel delay unit 2 as the signal of the target pixel (original signal) is to compensate for the delay due to the processing.

By the operations described above, the output signal  $S_f$  of the amplitude restricting circuit 7 will become the signal  $S_j$  after the amplitude of its absolute value is restricted to be not larger than the output signal  $S_i$  of the amplitude-restricting signal generator 6. The signal  $S_j$  is a high-frequency signal having its overshoot components removed, so that it is called "inclination-improving signal" in the present specification.

The inclination-improving signal  $S_j$  and the original signal  $S_c$  having its delay due to the processing for extracting the inclination-improving signal  $S_j$  compensated are added together at the adder 8, to become an edge-corrected signal  $S_p$  shown by solid line  $S_p$  in Fig. 3G.

As has been described, by applying an amplitude-restriction to the high-frequency signal  $S_f$  by means of the amplitude-restricting signal  $S_i$ , the edge-corrected signal  $S_p$  with the overshoots removed can be obtained.

In Embodiment 1, an image signal having the overshoots removed is obtained. But there are instances in which the image formed of signals with a certain amount of overshoots look sharper and better. In such a case, the amplitude adjusting circuit 65 forming part of the amplitude-restricting signal generator 6 may be used to vary and increase the amplitude of the amplitude-restricting signal  $S_i$  so as to include overshoot

components a little.

If the amplitude at the amplitude adjusting circuit 65 is adjusted as described above, so as to reduce the overshoots to an appropriate degree, rather than removing them completely, it is possible to obtain edge-corrected image signals having sharpness as well.

#### Embodiment 2.

Fig. 7 is an edge-correcting circuit of Embodiment 2 of the present invention. Signals appearing at various parts of the circuit of this embodiment are shown in Figs. 8A to 8H and Figs. 2A to 2F. The edge correcting circuit of this embodiment is generally identical to that of Embodiment 1, but is different in additionally having a subtractor 9, an amplitude control circuit 10, an amplitude adjusting circuit 11, and an adder 12.

The subtractor 9 subtracts the inclination-improving signal  $S_j$  output from the amplitude restricting circuit 7, from the high-frequency signal  $S_f$  output from the high-frequency signal extracting circuit 5, to produce an overshoot signal  $S_k$  shown in Fig. 8G.

The amplitude control circuit 10 adjusts the amplitude of the overshoot signal  $S_k$ , and restricts the amplitude to within a predetermined value, by clipping. The amplitude adjusting circuit 11 adjusts the amplitude of the inclination-improving signal  $S_j$  output from the amplitude restricting circuit 7.

The adder 12 adds the output of the amplitude control circuit 10 and the output of the amplitude adjusting circuit 11. The adder 8 adds the output of the adder 12, and the signal  $S_c$  which is a delay-compensated original signal, to produce an edge-corrected signal  $S_p$  shown in Fig. 8H.

As has been described, rather than adding the inclination-improving signal  $S_j$  (Fig. 3F) to the original signal to produce an edge-corrected signal, as in Embodiment 1, Embodiment 2 obtains an edge corrected signal  $S_p$  (Fig. 8H) having optimum overshoot components and inclination by: extracting an overshoot signal  $S_k$ , by subtracting the inclination-improving

signal  $S_j$  from the high-frequency signal  $S_f$ ; and at the same time, adjusting the amplitude of the inclination-improving signal  $S_j$ ; and determining the sum  $S_q$  of the amplitude-controlled overshoot signal  $S_k$  (the output of the amplitude control circuit 10) and the amplitude-adjusted inclination-improving signal (output of the amplitude adjusting circuit 11); and adding the sum  $S_p$  to the original signal  $S_c$ .

Incidentally, one of the amplitude control circuit 10 and the amplitude adjusting circuit 11 may be omitted.

According to Embodiment 2, the overshoot components and the components for improving the inclination of the edge can be adjusted independently, so that optimum edge correction can be achieved.

### **Embodiment 3.**

Fig. 9 shows an edge correcting circuit of Embodiment 3 of this invention. Signals appearing at various parts of the circuit of Embodiment 3 are shown in Figs. 10A to 10G and Figs. 2A to 2F. Embodiment 3 is generally identical to Embodiment 1, but the amplitude-restricting signal generator 6 of Fig. 1 is replaced by an amplitude-restricting signal generator 13.

The amplitude-restricting signal generator 13 differs from the amplitude-restricting signal generator 6 in that it receives the high-frequency signal  $S_f$  output from the high-frequency signal extracting circuit 5, in addition to the output signals  $S_b$  and  $S_c$  from the one-pixel delay units 1 and 2, and generates, therefrom, an amplitude-restricting signal  $S_i$  for removing the overshoot components.

Fig. 11 shows details of the amplitude-restricting signal generator 13 of Fig. 9. In Fig. 11, reference numeral identical to those in Fig. 5 denote identical or corresponding members. As illustrated in Fig. 11, the amplitude-restricting signal generator 13 has an input terminal 601 for receiving the output signal  $S_c$  of the one-pixel delay unit 2, an input terminal 602 for receiving the output signal  $S_b$  of the one-pixel delay unit 1, and an output terminal 603, like the amplitude-restricting

signal generator 6 of Fig. 5. It also has an input terminal 604 for receiving the high-frequency signal  $S_f$  output from the high-frequency signal extracting circuit 5.

The amplitude-restricting signal generator 13 also has a subtractor 61, a delay unit 67, a sign inverting circuit 68, and a selector 69. Like the subtractor 6 of Fig. 5, the subtractor 61 subtracts the signal  $S_c$  from the signal  $S_b$ , to produce a signal  $S_m$  shown in Fig. 10C. The output  $S_m$  of the subtractor 61 represents the result of the subtraction of the signal  $S_c$  of the target pixel from the signal  $S_b$  of a pixel shifted rightward by one pixel from the target pixel.

The one-pixel delay unit 67 delays the signal  $S_m$  by one pixel period. The sign inverting circuit 68 inverts the sign of the output signal of the one-pixel delay unit 67 to produce a signal  $S_n$  shown in Fig. 10D. The signal  $S_n$  is equivalent to the result of subtraction of the output signal  $S_c$  of the one-pixel delay unit 2 (i.e., the signal of the target pixel) from the output signal  $S_d$  of the one-pixel delay unit 3 (i.e., the signal of a pixel shifted leftward by one pixel from the target pixel).

The selector 69 receives the high-frequency signal  $S_f$ , the signal  $S_m$ , the signal  $S_n$ , and a signal representing tone "0," and selects one of the signal  $S_m$ , the signal  $S_n$ , and "0," and outputs the selected signal as the output signal  $S_r$  shown in Fig. 10E. If at least one of the signals  $S_m$  and  $S_n$  is zero or the signs of the signals  $S_m$  and  $S_n$  are identical, the selector 69 selects and outputs "0." If none of the signals  $S_m$  and  $S_n$  is zero, and the signs of the signals  $S_m$  and  $S_n$  are not identical, the selector 69 outputs that one of the signals  $S_m$  and  $S_n$  which has a sign identical to the high-frequency signal  $S_f$ . If the signal  $S_f$  is zero, it may be treated as positive or negative. In the illustrated example, it is treated as positive. In the illustrated example, the selector 69 receives the signal  $S_f$ , and determines the sign within the selector 69. However, a signal representing the sign of the signal  $S_f$  may be supplied to the selector 69. The output signal of the selector 69 is

passed as the amplitude control signal  $S_r$  through the output terminal 607 to the amplitude restricting circuit 7.

The rest of the operation is similar to that of Embodiment 1. That is, the amplitude restricting circuit 7 removes the overshoot components which are components having an amplitude not smaller than the amplitude-restricting signal  $S_r$ , from the high-frequency signal  $S_f$ , to produce the signal  $S_j$  shown in Fig. 10F. The adder 8 adds the signal  $S_j$  to the original signal  $S_c$ , and an edge-corrected signal  $S_p$  shown in Fig. 10G is obtained at the output terminal 102.

As has been described, according to Embodiment 3, an edge-corrected image signal with the overshoots removed can be obtained.

It was stated in connection with Embodiment 1 that the amplitude-restricting signal generator 6 may have a function of varying the amplitude of the amplitude-restricting signal. The amplitude-restricting signal generator 13 of Embodiment 3 may have the same function of varying the amplitude of the amplitude-restricting signal.

#### **Embodiment 4.**

Embodiment 2 is a modification of Embodiment 1 and is additionally provided with the subtractor 9, the amplitude control circuit 10, the amplitude adjusting circuit 11, and the adder 12 to enable adjustment of the overshoot signal  $S_k$  and the inclination-improving signal  $S_j$ , so that optimum picture quality can be obtained. Embodiment 3 may be modified in a similar manner.

Fig. 12 shows the configuration of an edge correcting circuit having such modifications as applied to Embodiment 3. The operations of the circuits 9, 10, 11 and 12 in Fig. 12 and the merits derived from the addition of these circuits are identical to those described in connection with Embodiment 2.

#### **Embodiment 5.**

Embodiment 1 employs, as a constituting element of the amplitude-restricting signal generator 6, the minimum value

selector 64 selecting the minimum value of the signals Sg and Sh. As an alternative, a maximum value selector 66 selecting the maximum value of the signals Sg and Sh may be used instead, as illustrated in Fig. 13. The signals appearing at various parts of the circuit of Fig. 13 are shown in Figs. 14A to 14G and Figs. 2A to 2F.

By using the maximum value selector in place of the minimum value selector 64, the amplitude-restricting signal Si, which is the output of the amplitude-restricting signal generator, will be as shown in Fig. 14E. The amplitude-restricting signal Si restricts the amplitude of the high-frequency signal Sf, and the inclination-improving signal Sj shown in Fig. 14F is obtained as the output signal of the amplitude restricting circuit 7. As the inclination-improving signal Sj is added to the signal Sc, which is a delay-compensated original signal, an edge-corrected signal Sp shown in Fig. 14G is produced.

#### **Embodiment 6.**

In Embodiments 1 to 5, one-pixel delay units are used to achieve horizontal edge correction. Replacement of the one-pixel delay units with one-line delay units will enable vertical edge correction. For instance, Fig. 15 shows an example in which the one-pixel delay units 1, 2, 3 and 4 in Fig. 1 have been replaced with one-line delay units 21, 22, 23 and 24.

#### **Variations.**

In the above embodiments, the signal of the target pixel, and the signals of the pixels shifted by two pixels from the target pixel are used to extract a high-frequency signal of the image, and the signal of the target pixel, and the signals of the pixels shifted by one pixel from the target pixel are used to generate an amplitude-restricting signal. To generalize, the signal of the target pixel, and the signals of the pixels shifted by m (m being an integer not smaller than two) pixels from the target pixel may be used to extract a high-frequency signal of the image, and the signal of the target pixel, and the signals of the pixels shifted by n (n being an integer not



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